



# Application Note

## Porting Z-Wave Appl. SW from ZW0102 to ZW0201

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**REVISION RECORD**

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|-----------------|-------------|------------|-----------------------|---|
| 1               | 20050114    | SSE<br>JFR | ALL                   | Minor changes   |
| 1.01            | 20050411    | SSE        | ALL                   | Made changes according to NTJ notes.                        |
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| 3               | 20060905    | JFR        | Front page            | Change title  |
| 4               | 20061023    | JFR        | Section 3.8           | RF_MODE and IDLE_MODE removed                               |

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## 1 ABBREVIATIONS

| Abbreviation | Explanation                                 |
|--------------|---|
| ADC          | Analog to Digital Converter                 |
| API          | Application Programming Interface.          |
| ISR          | Interrupt Service Routine                   |
| PWM          | Pulse Width Modulation                      |
| RTC          | Real Time Clock                             |
| UART         | Universal Asynchronous Receiver/Transmitter |
| WUT          | Wake Up Timer                               |

## 2 INTRODUCTION

### 2.1 Purpose

The purpose of this document is to give guidelines for the Z-Wave application developer, when porting software applications from ZW0102 to ZW0201 platform.

### 2.2 Audience and prerequisites

The audience of this document is Z-Wave partners and Zensys A/S.

### 3 ZW0201 PORTING ISSUES

#### 3.1 System Clock

The system clock (**fsystem**) in ZW0201 is 16Mhz in opposite to 7.3769MHz in ZW0102.

The 8051 timers 0 and 1 runs on half the system clock rate.

#### 3.2 ZW0201 UART

The ZW0201 UART supports the following baud rates: 9600kbps, 38400kbps and 115200kbps. The ZW0201 UART API is extended with the following API functions:

|                     |   |
|---------------------|---|
| <b>UART_ClearRx</b> | Clear the UART byte received flag. Useful when using serial interrupt service routine.      |
| <b>UART_ClearTx</b> | Clear the UART byte sent flag. Useful when using serial interrupt service routine.          |
| <b>UART_Read</b>    | Read the UART receive register. Useful when using serial interrupt service routine.         |
| <b>UART_Write</b>   | Write a byte to the UART send register. Useful when using serial interrupt service routine. |
| <b>UART_Enable</b>  | Enable the UART controller.   |
| <b>UART_Disable</b> | Disable the UART controller.  |

When Porting from ZW0102 to ZW0201, the developer only need to change the baud rates used.

### 3.3 ZW0201 Timer

The PWM API has the same functions as the ZW0102, except for the new API function ZW\_PWMSetup parameter bit mask. The bit mask for the ZW\_PWMSetup parameter is as followed:

|         |  |
|---------|--|
| Bit 0   | 0 = Timer is inactive and counter is cleared.<br>1 = Timer is active and counter is enabled. |
| Bit 1   | 0 = TIMER mode<br>1 = PWM mode   |
| Bit 2   | 0 = Timer counter runs on fsystem/4.<br>1 = Timer counter runs on fsystem/512.               |
| Bit 3   | 0 = Timer stops upon overflow.<br>1 = Timer reloads its counter registers upon overflow.     |
| Bit 4-7 | Don't care   |

### 3.4 ZW0201 ADC

The Z-Wave ADC API for ZW0201 is changed as follow:

1. The ADC\_Init Function has 4 parameters. In ZW0201 supports the selection of the mode, the upper reference voltage, lower reference voltage and the input pin
2. ZW0201's ADC has 4 input pins. The 4 pins are multiplexed; only one pin is active at one time.
3. ZW0201's ADC has 2 modes. Single conversion mode and continuous mode, continuous mode is only supported in 8 bit mode. The ADC\_MULTI\_STP\_MODE and ADC\_MULTI\_RST\_MODE are not supported in ZW0201.
4. **ADC\_On** Is obsolete in ZW0201. The ADC\_Off function is used to power down the ADC. The ADC\_Init function must be used to power up the ADC.
5. **ADC\_SetThresMode** Is used to set the threshold mode. In ZW0201 ADC can trigger when input below/equal or above/equal threshold value.
6. **ADC\_SetResolution** Is used to set the ADC resolution. The ZW0201 ADC can either work with 8-bit or 12-bit resolution.
7. **ADC\_SetAZPL** Is used to set the auto zero period length. See [1] for more details.
8. **ADC\_Buf** is used to enable a buffer between the analog input and the A/D converter. See [1] for more details.
9. **ADC\_IsFired**. Is used to check if the conversion result crossed the threshold value.
10. **ADC\_SetSamplingRate**. Is obsolete, ZW0201 has a fixed sampling rate.

### 3.5 ZW0201 TRIAC

The API function TRIAC\_Init parameters have changed. See [1] for more details.

### 3.6 RTC

ZW0201 don't have internal support for a Real Time Clock. To implement this functionality, the developer can use a system timer for listening devices. For battery devices (not listening) the WUT can be used, see [1] for more details on WUT.

### 3.7 Non Initialized Variables

A memory area of 16 SRAM bytes starting at address 0x07DD in controllers and 0x07F0 in slaves will not be initialized when the application starts. This allows the application to have SRAM based variables transferring values from the previous state. A typical case could be to preserve data when the ZW0201 node enters WUT or stop mode. The Z-Wave protocol will initialize the remaining part of the SRAM at wake up on the ZW0201.

The NON\_ZERO\_START\_ADDR constant defines the start address. The following example shows how to define a byte and word in the non-initialized variables area:

```
WORD var1 _at_ NON_ZERO_START_ADDR;  
BYTE var2 _at_ NON_ZERO_START_ADDR + 2;
```

### 3.8 Power Management

Power management in ZW0201 has 3 new API functions. These functions are:

**ZW\_SetSleepMode:** The ZW0201 can be configured to one of the following power down modes:

1. **STOP\_MODE:** ZW0201 wake up based on a hardware reset or an external interrupt.
2. **WUT\_MODE:** ZW0201 wake up based on WUT time out or an external interrupt. The ZW0201 is reset when it wake up.

**ZW\_SetWutTimeout:** sets the WUT time out value.

**ZW\_IsWutKicked:** When the ZW0201 wake up from WUT mode, the API function determines if the ZW0201 reset was caused by the WUT.

### 3.9 Watchdog

The ZW0201 contains a watchdog to increase reliability by detecting software and/or hardware anomalies and reset the ZW0201 if any occur. The watchdog timeout is 1.05 seconds and is fixed. The watchdog is disabled in the protocol by default.

To control the watchdog three API functions are provided.

**ZW\_WatchDogEnable:** Enable the watchdog.

**ZW\_WatchDogDisable:** Disable the watchdog.

**ZW\_WatchDogKick:** Restart the watchdog and thereby preventing it from timing out.

## 4 REFERENCES

[1] Zensys, INS10247, Instruction, Z-Wave ZW0102/ZW0201 Application Programming Guide